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A matheuristic solution approach for the optimal design of multiproduct batch plants with parallel production lines

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Outline

Batch plant design

Introduction parallel production lines

Mathuristic solution approach

Results

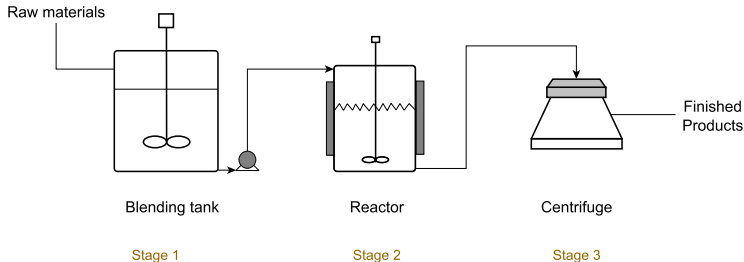
Conclusion and future work



Batch process

What Production of fine and specialty chemicals:
e.g. pharmaceuticals, food additives, lubricants.

How Finite quantities made in discrete batches



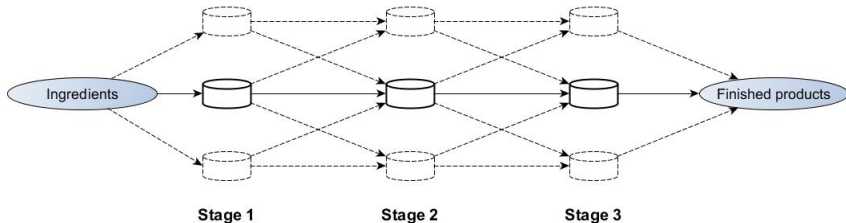


Batch plant design

Optimisation problem - min. capital cost

Given the product volumes needed, recipes and production horizon:

Determine optimal **number** and **size** of batch equipment units for every stage, out of a discrete set of sizes, so as to minimise capital costs while satisfying design and horizon constraints



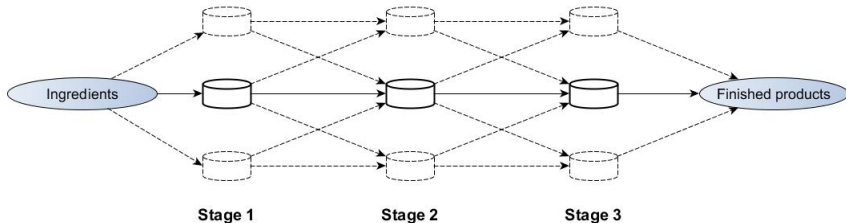


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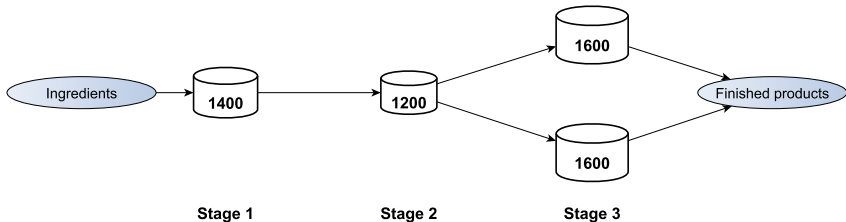


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Majority of literature: MI(N)LP model - solved exactly [1, 2]

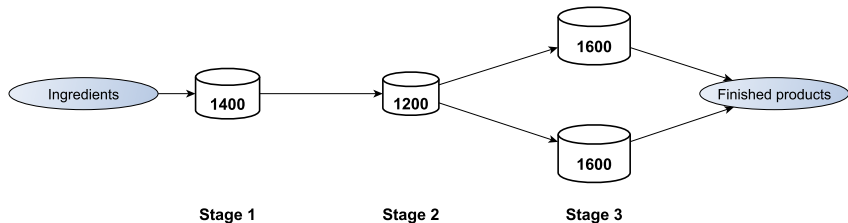


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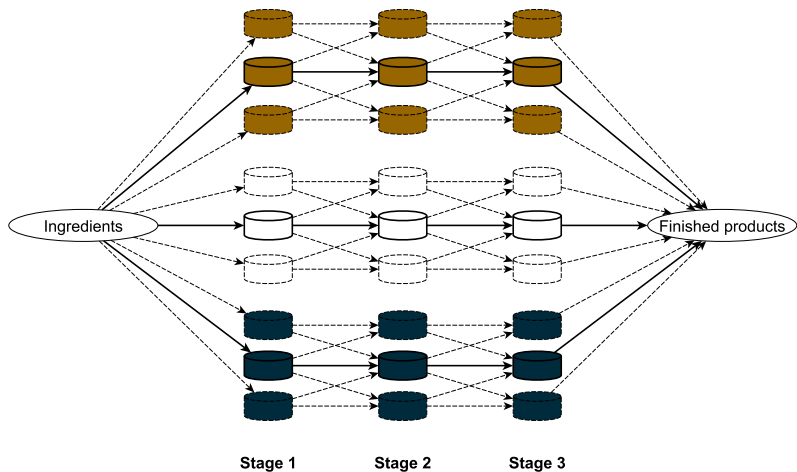


Majority of literature: MI(N)LP model - solved exactly [1, 2]



New design option - parallel lines

Optimisation problem - min. capital and setup costs [3]

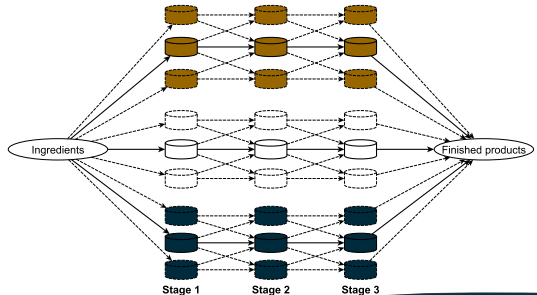




Parallel production lines

Characteristics:

- ▶ Installed on 1 production site
- ▶ Operate independently but simultaneously
- ▶ Consist of all stages
- ▶ Distribution of products over lines

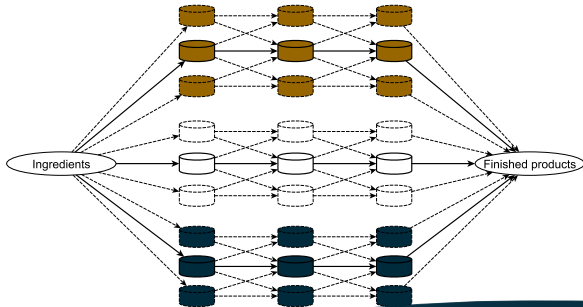




Parallel production lines

Extension of the design problem - Determine:

- ▶ Number of lines to install
- ▶ Number and size of equipment units per stage per installed line
- ▶ Assignment of production to installed lines
 - ▶ a product can be produced on multiple production lines
(= product duplication)

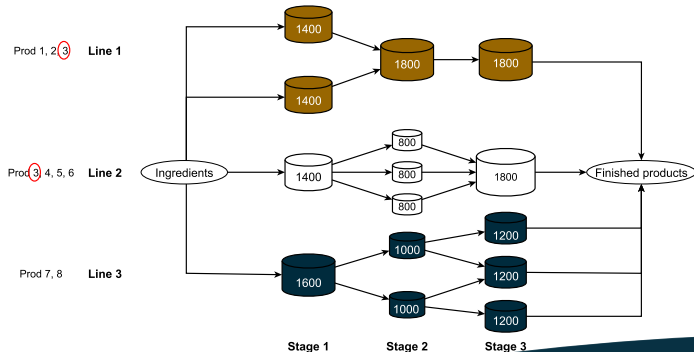




Parallel production lines

Extension of the design problem - Determine:

- ▶ Number of lines to install
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Parallel production lines

Extension of the design problem - Determine:

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 - ▶ a product can be produced on multiple production lines

→ becomes intractable for exact solution methods
when problems are larger

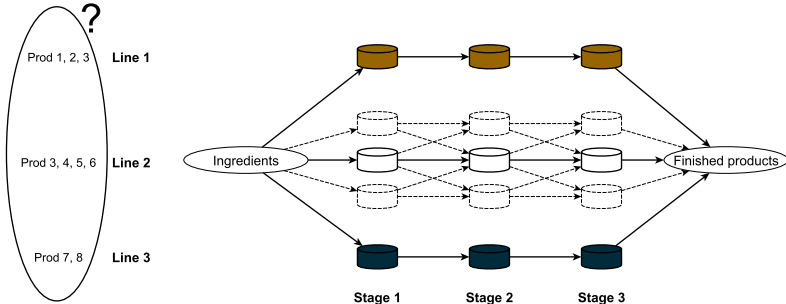


Mathuristic Decomposition approach

Decomposition heuristic: divide problem into subproblems

- ▶ Product to line assignment
- ▶ Design problem

Including feedback loops



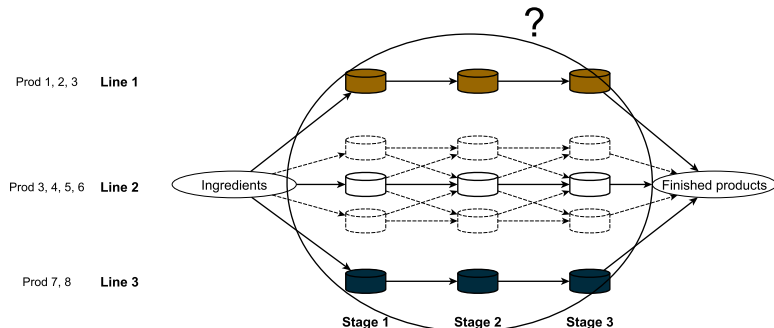


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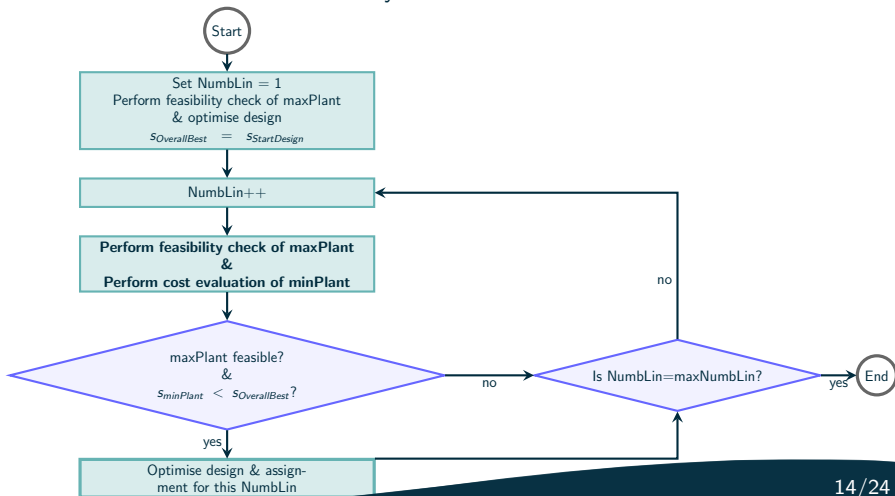




Global procedure

Set number of lines

1. Single line - only design problem
2. Multiple lines - design and assignment problem
 - ▶ 2 Evaluations: feasibility and cost





Evaluate costs

Cost evaluation of minPlant considers:

- ▶ Capital costs: cost for acquiring/installing equipment
- ▶ Startup costs: costs for preparing the equipment for the production run of every product
- ▶ Contamination costs: penalisation for producing products of different families on the same equipment

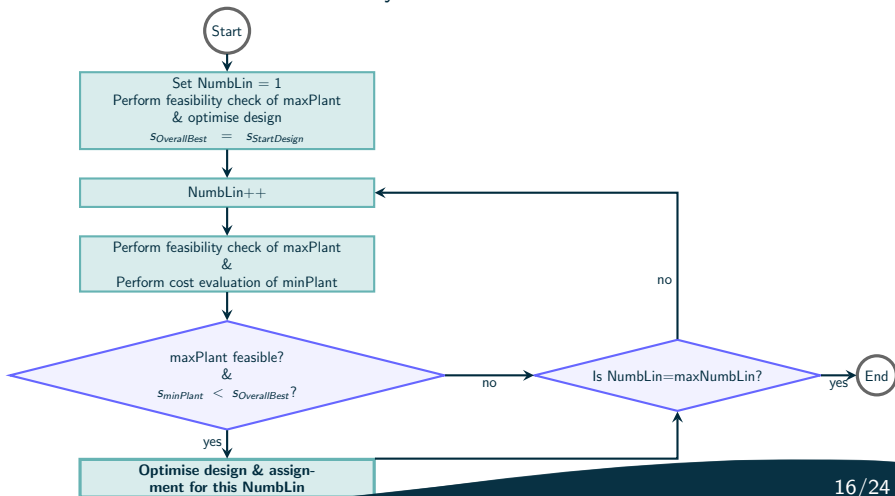
Used as objective function in later optimisations

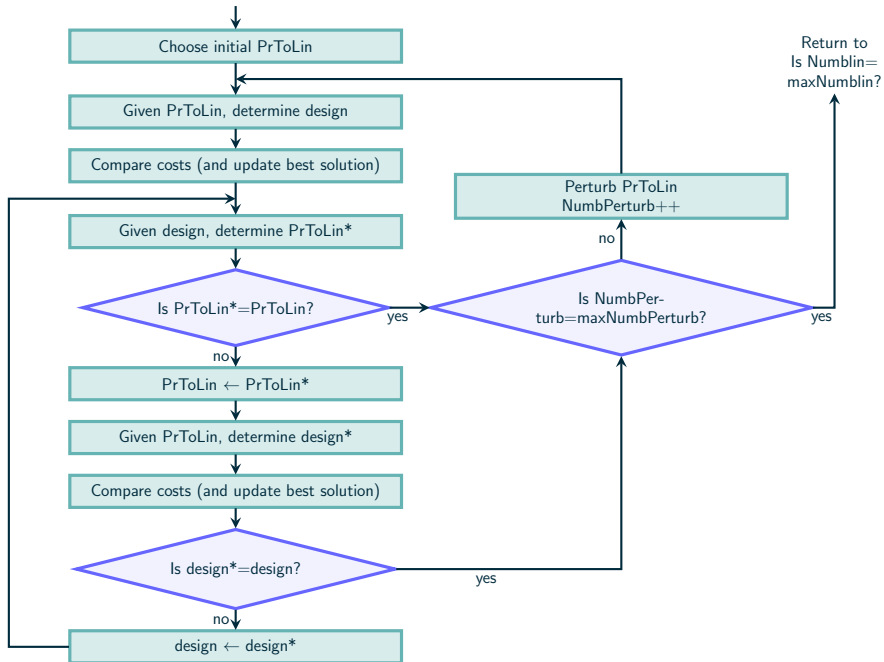


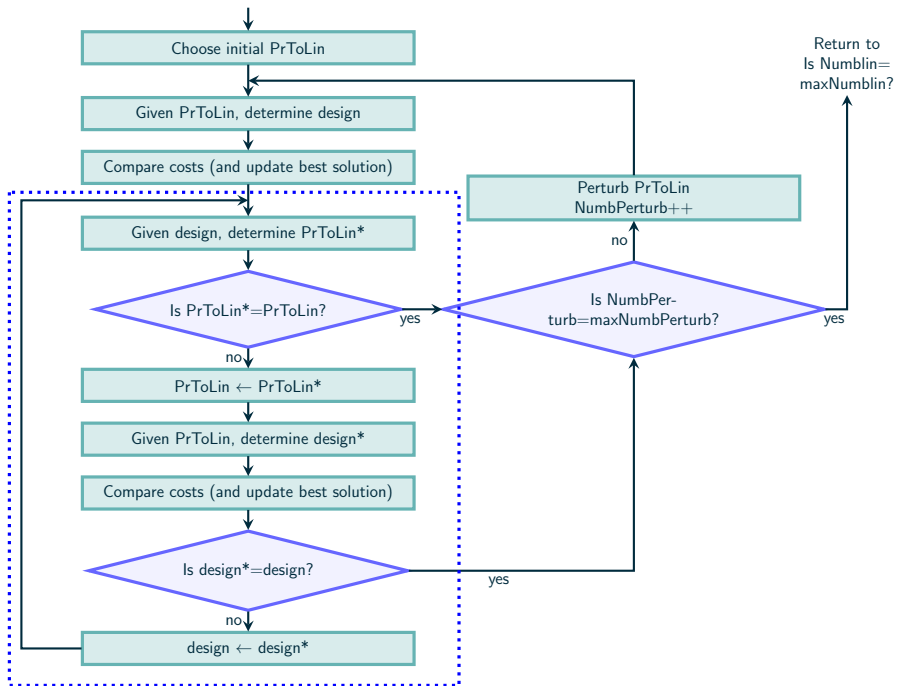
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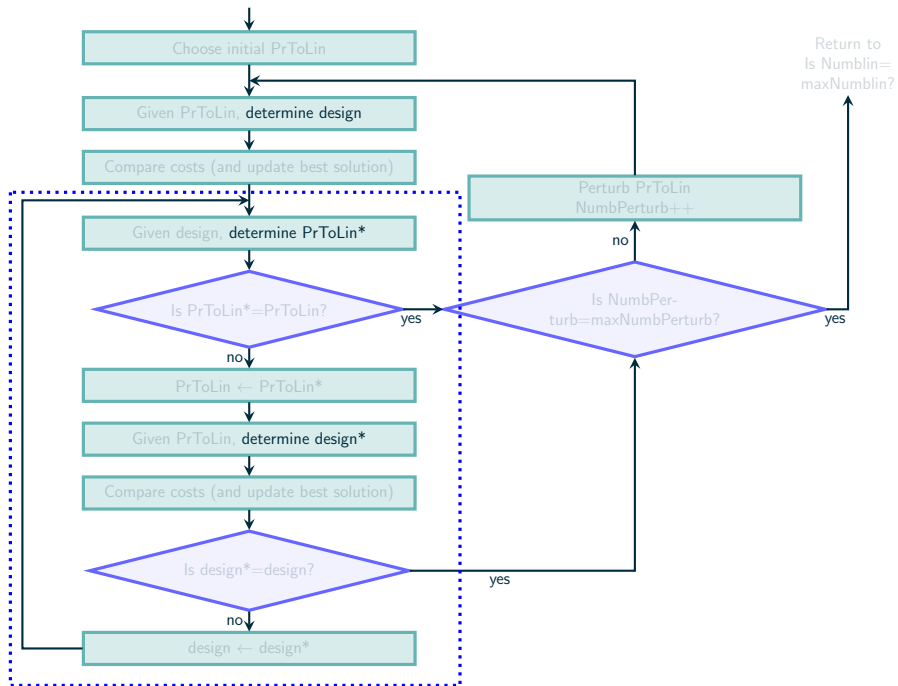
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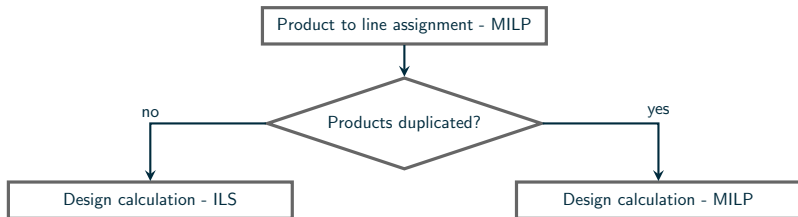




Solution techniques

Solve each subproblem:

- ▶ Product to line assignment, with given design:
MILP, exact solver
- ▶ Design problem, with given line assignment
 - ▶ Metaheuristic: Iterated local search [4, 5]
 - ▶ MILP, exact solver





	Opt. sol. (Gurobi)	CPU (sec)	Best math. sol. ¹	gap (%)	CPU (sec)
10 products					
Ca.	128 808	351.1	128 808	0	19.64
Ca.St.	166 947	5230.5	167 281	0.2	0.58
Ca.St.Co.	168 588	38.0	168 588	0	1.73
28 products					
Ca.	115 065	213.74	115 065	0	42.37
Ca.St.	173 035	661.47	173 035	0	1.60
Ca.St.Co.	180 747	1179.85	181 035	0.2	4.97
40 products					
Ca.	96 517	3551.62	96 517	0	262.14
Ca.St.	996 517	4892.11	996 517	0	1.85
Ca.St.Co.	1 016 517	5282.02	1 016 517	0	1.74
50 products					
Ca.	432 133	516.08	432 133	0	0.03
Ca.St.	797 696	313.15	797 696	0	1.91
Ca.St.Co.	826 496	912.57	826 496	0	2.55
60 products					
Ca.	6958	753.87	6958	0	0.03
Ca.St.	24 958	819.74	24 958	0	0.03
Ca.St.Co.	26 158	1543.72	26 165	0.02	0.04
75 products					
Ca.	1 872 676 (gap: 85%)	14 400	1 759 634	-	6058.09
Ca.St.	no feas sol (LB:358 081)	14 400	1 981 117	-	1388.46
Ca.St.Co.	no feas sol (LB: 374 894)	14 400	2 013 775	-	4509.8
150 products					
Ca.	336 689 (gap: 89 %)	14 400	228 944	-	7847.64
Ca.St.	20 932 033 (gap: 97%)	14 400	822 612	-	370.99
Ca.St.Co.	23 620 033 (gap: 98%)	14 400	1 001 958	-	65.47

¹out of 10 runs



Aim: Determine design of multiproduct chemical batch plants with parallel lines

Contributions: An efficient mathematical is developed, for solving the batch plant design problem

Future research:

- ▶ Improve MILP calculations
- ▶ Thoroughly test algorithm



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- [2] A. P. Barbosa-Póvoa, “A critical review on the design and retrofit of batch plants,” *Computers & Chemical Engineering*, vol. 31, no. 7, pp. 833 – 855, 2007.
- [3] F. Verbiest, T. Cornelissens, and J. Springael, “Design of a chemical batch plant with parallel production lines: Plant configuration and cost effectiveness,” *Computers & Chemical Engineering*, vol. 99, pp. 21 – 30, 2017.
- [4] H. R. Lourenço, O. C. Martin, and T. Stütze, “Iterated local search: Framework and applications,” in *Handbook of Metaheuristics* (M. Gendreau and J.-Y. Potvin, eds.), vol. 146 of *International Series in Operations Research & Management Science*, pp. 363–397, Springer US, 2010.
- [5] K. Sörensen and F. W. Glover, *Metaheuristics*, pp. 960–970. Boston, MA: Springer US, 2013.



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Appendix





Calculate Design

Iterated Local Search [1]

Algorithm : Iterated Local Search

```
 $s_0 \leftarrow \text{InitialSolution}$   
 $s \leftarrow \text{LocalSearch}(s_0)$   
while Termination criterion is not met do  
   $s' \leftarrow \text{perturbation}(s)$   
   $s'' \leftarrow \text{LocalSearch}(s')$   
   $s \leftarrow \text{AcceptanceCriterion}(s'', s^*)$   
end while
```

- ▶ Initial Solution: max. design (max. number of units, max. sizes)
 - ▶ Local Search - moves:
 - ▶ Decrease number of units for one stage
 - ▶ Decrease size of units for one stage
- Move strategy: steepest descent
- ▶ Perturbation: reset certain % of stages to the maximum
 - ▶ Termination criterion: stop after n iterations without improvement of the best solution found so far



Mathematical model - Single line

Basic design model - non-linear

$$\min \sum_{j=1}^J n_j \alpha_j V_j^{\beta_j} \quad \alpha_j, \beta_j: \text{ cost coefficients}$$

s.t.

Design constraint:

$$V_j \geq S_{ij} B_i \quad \forall i, j \quad (1)$$

Horizon constraint:

$$T_i = \max_{j=1, \dots, J} \left(\frac{\tau_{ij}}{n_j} \right) \quad \forall i \quad (2)$$

$$\theta_i = n_i T_i \quad \forall i \quad (3)$$

$$\sum_{i=1}^P n_i T_i \leq H \quad (4)$$

$$Q_i = n_i B_i \quad \forall i \quad (5)$$

Rewrite (3), (4) and (5)

$$\sum_{i=1}^P \frac{Q_i T_i}{B_i} \leq H \quad (6)$$

$$V_j^{LL} \leq V_j \leq V_j^{UL} \quad \forall j; B_i, T_i \geq 0 \quad \forall i; n_i \in \mathbb{N}$$



Mathematical model - Parallel lines

Capital costs

$$\min \sum_{l=1}^L \sum_{j=1}^J \sum_{s=1}^S \sum_{n=1}^N \alpha_j v_s^{\beta_j} z_{ljn} u_{ljs} \quad \alpha_j, \beta_j: \text{cost coefficients and } \beta_j < 1$$

with v_s : volume of the equipment and

$$z_{ljn} = \begin{cases} 1 & \text{if unit } n \text{ of stage } j \text{ of line } l \text{ exists} \\ 0 & \text{otherwise} \end{cases}$$

and

$$u_{ljs} = \begin{cases} 1 & \text{if equipment of stage } j \text{ of line } l \text{ has size } s \\ 0 & \text{otherwise} \end{cases}$$



Mathematical model - Parallel lines

Startup costs

$$\min \sum_{i=1}^P \sum_{l=1}^L \sum_{j=1}^J \sum_{n=1}^N Cstart_i z_{ljn} t_{li}$$

with

$$z_{ljn} = \begin{cases} 1 & \text{if unit } n \text{ of stage } j \text{ of line } l \text{ exists} \\ 0 & \text{otherwise} \end{cases}$$

$$t_{li} = \begin{cases} 1 & \text{if product } i \text{ is produced on line } l \\ 0 & \text{otherwise} \end{cases}$$

and $Cstart_i$ is a line and stage independent startup cost.



Mathematical model - Parallel lines

Contamination cost

$$\min \sum_{l=1}^L \sum_{f=1}^F \sum_{j=1}^J \sum_{n=1}^N C_{cont} b_{fl} z_{ljn} g_l$$

$$b_{fl} \geq d_{if} t_{li} \quad \forall l, f, i \quad (1)$$

$$\sum_{f=1}^F b_{fl} \geq 2 - M(1 - g_l) \quad \forall l \quad (2)$$

$$\sum_{f=1}^F b_{fl} - 1 \leq M g_l \quad \forall l \quad (3)$$

with

$$b_{fl} = \begin{cases} 1 & \text{if product family } f \text{ is produced on line } l \\ 0 & \text{otherwise} \end{cases}$$

and g_l a correction binary to avoid costs if there is only 1 pf and C_{cont} a fixed cost



Mathematical model - Parallel lines

Production line design constraints

$$z_{ljn} = \begin{cases} 1 & \text{if unit } n \text{ of stage } j \text{ of line } l \text{ exists} \\ 0 & \text{otherwise} \end{cases}$$

$$t_{li} = \begin{cases} 1 & \text{if product } i \text{ is produced on line } l \\ 0 & \text{otherwise} \end{cases}$$

$$\sum_{n=1}^N z_{lj'n} \leq N \sum_{n=1}^N z_{ljn} \quad \forall l, j, j' \quad (4)$$

$$z_{ljn} \geq z_{lj(n+1)} \quad \forall l, j, n \text{ with } n < N \quad (5)$$

$$t_{li} \leq \sum_{n=1}^N z_{ljn} \quad \forall l, j, i \quad (6)$$

$$\sum_{l=1}^L t_{li} \geq 1 \quad \forall i \quad (7)$$



Mathematical model - Parallel lines

Equipment design constraints

$$u_{ljs} = \begin{cases} 1 & \text{if equipment of stage } j \text{ of line } l \text{ has size } s \\ 0 & \text{otherwise} \end{cases}$$

$$\sum_{n=1}^N z_{ljn} \leq N \sum_{s=1}^S u_{ljs} \quad \forall l, j \quad (8)$$

$$\sum_{n=1}^N z_{ljn} \geq \sum_{s=1}^S u_{ljs} \quad \forall l, j \quad (9)$$

$$\sum_{s=1}^S u_{ljs} \leq 1 \quad \forall l, j \quad (10)$$

$$n_{li} \geq \sum_{s=1}^S \frac{q_{li} S_{ij}}{v_s} u_{ljs} \quad \forall l, j, i \quad (11)$$



Mathematical model - Parallel lines

Horizon constraints

$$\sum_{n=1}^N z_{ljn} T_{lji} = n_{li} \tau_{ij} \quad \forall l, j, i \quad (12)$$

$$\theta_{li} \geq T_{lji} \quad \forall l, j, i \quad (13)$$

$$\sum_{i=1}^P \theta_{li} \leq H \quad \forall l \quad (14)$$



Mathematical model - Parallel lines

Demand constraint & Boundaries

$$\sum_{l=1}^L q_{li} = Q_i \quad \forall i \quad (15)$$

$$z_{ljn}, t_{li}, u_{ljs} \in \{0, 1\} \quad (16)$$

$$q_{li}, n_{li}, T_{lji}, \theta_{li} \geq 0 \quad (17)$$

$$q_{li} \leq Q_i t_{li} \quad \forall l, i \quad (18)$$

$$n_{li} \leq M_i t_{li} \quad \forall l, i \quad (19)$$

$$T_{lji} \leq H t_{li} \quad \forall l, j, i \quad (20)$$

$$\theta_{li} \leq H t_{l,j,i} \quad \forall l, i \quad (21)$$

$$\epsilon t_{li} \leq q_{li} \quad \forall l, i \quad (22)$$



Size factor

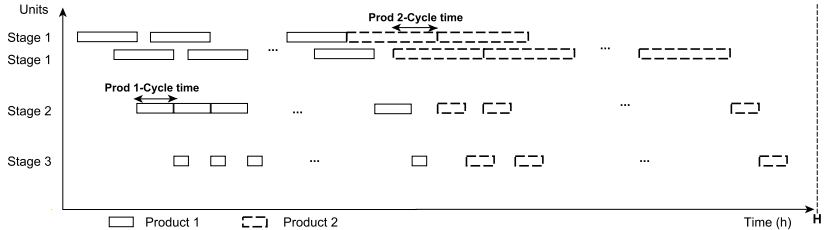
S_{ij} : characteristic size of equipment needed at stage j to produce unit mass of product i

\approx density

= since each product has different characteristics, the sizes of equipment needed to produce the same mass of product will vary from product to product



Single product campaigns





Bibliography

- [1] H. R. Lourenço, O. C. Martin, and T. Stützle, “Iterated local search: Framework and applications,” in *Handbook of Metaheuristics* (M. Gendreau and J.-Y. Potvin, eds.), vol. 146 of *International Series in Operations Research & Management Science*, pp. 363–397, Springer US, 2010.



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Appendix

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